Notes and problems for Desai chapter IV.

Originally appeared at:

http://sites.google.com/site/peeterjoot/math2010/desaiCh4.pdf

Contents

2.4.1 Statement. 2.4.2 Solution. 2.5 Problem 5. 2.5.1 Statement. 2.5.2 Solution. 2.6 Problem 6. 2.6.1 Statement. 2.6.2 Solution. 2.7 Problem 7. 2.7.1 Statement.	1	Not	S.	2
1.2.1 Vatche's explaination. 1.3 Another question on raising and lowering arguments. 2 Problems 2.1 Problem 1. 2.1.1 Statement. 2.1.2 Cartesian case. 2.1.3 Rectangular normalization. 2.1.4 Infinite space normalization. 2.1.5 Polar case. 2.2 Problem 2. 2.2.1 Statement. 2.2.2 Solution. 2.3 Problem 3. 2.3.1 Statement. 2.3.2 Solution. 2.4 Problem 4. 2.4.1 Statement. 2.4.2 Solution. 2.5 Problem 5. 2.5.1 Statement. 2.5.2 Solution. 2.6 Problem 6. 2.6.1 Statement. 2.6.2 Solution. 2.7 Problem 7. 2.7.1 Statement.		1.1	Antisymmetric tensor summation identity	2
1.3 Another question on raising and lowering arguments. 2 Problems 2.1 Problem 1. 2.1.1 Statement. 2.1.2 Cartesian case. 2.1.3 Rectangular normalization. 2.1.4 Infinite space normalization. 2.1.5 Polar case. 2.2 Problem 2. 2.2.1 Statement. 2.2.2 Solution. 2.3 Problem 3. 2.3.1 Statement. 2.3.2 Solution. 2.4 Problem 4. 2.4.1 Statement. 2.4.2 Solution. 2.5 Problem 5. 2.5.1 Statement. 2.5.2 Solution. 2.6 Problem 6. 2.6.1 Statement. 2.6.2 Solution. 2.7 Problem 7. 2.7.1 Statement.		1.2	Question on raising and lowering arguments	2
2 Problems 2.1 Problem 1. 2.1.1 Statement. 2.1.2 Cartesian case. 2.1.3 Rectangular normalization. 2.1.4 Infinite space normalization. 2.1.5 Polar case. 2.2 Problem 2. 2.2.1 Statement. 2.2.2 Solution. 2.3 Problem 3. 2.3.1 Statement. 2.3.2 Solution. 2.4 Problem 4. 2.4.1 Statement. 2.4.2 Solution. 2.5 Problem 5. 2.5.1 Statement. 2.5.2 Solution. 2.6 Problem 6. 2.6.1 Statement. 2.6.2 Solution. 2.7 Problem 7. 2.7.1 Statement.			1.2.1 Vatche's explaination	3
 2.1.1 Statement. 2.1.2 Cartesian case. 2.1.3 Rectangular normalization. 2.1.4 Infinite space normalization. 2.1.5 Polar case. 2.2 Problem 2. 2.2.1 Statement. 2.2.2 Solution. 2.3 Problem 3. 2.3.1 Statement. 2.3.2 Solution. 2.4 Problem 4. 2.4.1 Statement. 2.4.2 Solution. 2.5 Problem 5. 2.5.1 Statement. 2.5.2 Solution. 2.6 Problem 6. 2.6.1 Statement. 2.6.2 Solution. 2.7 Problem 7. 2.7.1 Statement. 		1.3	Another question on raising and lowering arguments	3
2.1.1 Statement. 2.1.2 Cartesian case. 2.1.3 Rectangular normalization. 2.1.4 Infinite space normalization. 2.1.5 Polar case. 2.2 Problem 2. 2.2.1 Statement. 2.2.2 Solution. 2.3 Problem 3. 2.3.1 Statement. 2.3.2 Solution. 2.4 Problem 4. 2.4.1 Statement. 2.4.2 Solution. 2.5 Problem 5. 2.5.1 Statement. 2.5.2 Solution. 2.6 Problem 6. 2.6.1 Statement. 2.6.2 Solution. 2.7 Problem 7. 2.7.1 Statement.	2	Prol	lems	4
2.1.2 Cartesian case. 2.1.3 Rectangular normalization. 2.1.4 Infinite space normalization. 2.1.5 Polar case. 2.2 Problem 2. 2.2.1 Statement. 2.2.2 Solution. 2.3 Problem 3. 2.3.1 Statement. 2.3.2 Solution. 2.4 Problem 4. 2.4.1 Statement. 2.4.2 Solution. 2.5 Problem 5. 2.5.1 Statement. 2.5.2 Solution. 2.6 Problem 6. 2.6.1 Statement. 2.6.2 Solution. 2.7 Problem 7. 2.7.1 Statement.		2.1	Problem 1	4
2.1.3 Rectangular normalization. 2.1.4 Infinite space normalization. 2.1.5 Polar case. 2.2 Problem 2. 2.2.1 Statement. 2.2.2 Solution. 2.3 Problem 3. 2.3.1 Statement. 2.3.2 Solution. 2.4 Problem 4. 2.4.1 Statement. 2.4.2 Solution. 2.5 Problem 5. 2.5.1 Statement. 2.5.2 Solution. 2.6 Problem 6. 2.6.1 Statement. 2.6.2 Solution. 2.7 Problem 7. 2.7.1 Statement.			2.1.1 Statement	4
2.1.4 Infinite space normalization. 2.1.5 Polar case. 2.2 Problem 2. 2.2.1 Statement. 2.2.2 Solution. 2.3 Problem 3. 2.3.1 Statement. 2.3.2 Solution. 2.4 Problem 4. 2.4.1 Statement. 2.4.2 Solution. 2.5 Problem 5. 2.5.1 Statement. 2.5.2 Solution. 2.6 Problem 6. 2.6.1 Statement. 2.6.2 Solution. 2.7 Problem 7. 2.7.1 Statement.			2.1.2 Cartesian case	4
2.1.5 Polar case. 2.2 Problem 2. 2.2.1 Statement. 2.2.2 Solution. 2.3 Problem 3. 2.3.1 Statement. 2.3.2 Solution. 2.4 Problem 4. 2.4.1 Statement. 2.4.2 Solution. 2.5 Problem 5. 2.5.1 Statement. 2.5.2 Solution. 2.6 Problem 6. 2.6.1 Statement. 2.6.2 Solution. 2.7 Problem 7. 2.7.1 Statement.			2.1.3 Rectangular normalization	5
 2.2 Problem 2.			2.1.4 Infinite space normalization.	6
2.2.1 Statement. 2.2.2 Solution. 2.3 Problem 3. 2.3.1 Statement. 2.3.2 Solution. 2.4 Problem 4. 2.4.1 Statement. 2.4.2 Solution. 2.5 Problem 5. 2.5.1 Statement. 2.5.2 Solution. 2.6 Problem 6. 2.6.1 Statement. 2.6.2 Solution. 2.7 Problem 7. 2.7.1 Statement.			2.1.5 Polar case	6
2.2.2 Solution. 2.3 Problem 3. 2.3.1 Statement. 2.3.2 Solution. 2.4 Problem 4. 2.4.1 Statement. 2.4.2 Solution. 2.5 Problem 5. 2.5.1 Statement. 2.5.2 Solution. 2.6 Problem 6. 2.6.1 Statement. 2.6.2 Solution. 2.7 Problem 7. 2.7.1 Statement.		2.2	Problem 2	7
 2.3 Problem 3. 2.3.1 Statement. 2.3.2 Solution. 2.4 Problem 4. 2.4.1 Statement. 2.4.2 Solution. 2.5 Problem 5. 2.5.1 Statement. 2.5.2 Solution. 2.6 Problem 6. 2.6.1 Statement. 2.6.2 Solution. 2.7 Problem 7. 2.7.1 Statement. 			2.2.1 Statement	7
2.3.1 Statement. 2.3.2 Solution. 2.4 Problem 4. 2.4.1 Statement. 2.4.2 Solution. 2.5 Problem 5. 2.5.1 Statement. 2.5.2 Solution. 2.6 Problem 6. 2.6.1 Statement. 2.6.2 Solution. 2.7 Problem 7. 2.7.1 Statement.			2.2.2 Solution	8
2.3.2 Solution. 2.4 Problem 4. 2.4.1 Statement. 2.4.2 Solution. 2.5 Problem 5. 2.5.1 Statement. 2.5.2 Solution. 2.6 Problem 6. 2.6.1 Statement. 2.6.2 Solution. 2.7 Problem 7. 2.7.1 Statement.		2.3	Problem 3	9
 2.4 Problem 4. 2.4.1 Statement. 2.4.2 Solution. 2.5 Problem 5. 2.5.1 Statement. 2.5.2 Solution. 2.6 Problem 6. 2.6.1 Statement. 2.6.2 Solution. 2.7 Problem 7. 2.7.1 Statement. 			2.3.1 Statement	9
2.4.1 Statement. 2.4.2 Solution. 2.5 Problem 5. 2.5.1 Statement. 2.5.2 Solution. 2.6 Problem 6. 2.6.1 Statement. 2.6.2 Solution. 2.7 Problem 7. 2.7.1 Statement.			2.3.2 Solution	9
2.4.2 Solution. 2.5 Problem 5. 2.5.1 Statement. 2.5.2 Solution. 2.6 Problem 6. 2.6.1 Statement. 2.6.2 Solution. 2.7 Problem 7. 2.7.1 Statement.		2.4	Problem 4	10
 2.5 Problem 5. 2.5.1 Statement. 2.5.2 Solution. 2.6 Problem 6. 2.6.1 Statement. 2.6.2 Solution. 2.7 Problem 7. 2.7.1 Statement. 			2.4.1 Statement	10
2.5.1 Statement. 2.5.2 Solution. 2.6 Problem 6. 2.6.1 Statement. 2.6.2 Solution. 2.7 Problem 7. 2.7.1 Statement.			2.4.2 Solution	10
2.5.2 Solution. 2.6 Problem 6. 2.6.1 Statement. 2.6.2 Solution. 2.7 Problem 7. 2.7.1 Statement.		2.5	Problem 5	10
2.6 Problem 6. 2.6.1 Statement. 2.6.2 Solution. 2.7 Problem 7. 2.7.1 Statement.			2.5.1 Statement	10
2.6 Problem 6. 2.6.1 Statement. 2.6.2 Solution. 2.7 Problem 7. 2.7.1 Statement.			2.5.2 Solution	10
2.6.2 Solution		2.6		
2.6.2 Solution			2.6.1 Statement	11
2.7 Problem 7. 2.7.1 Statement.				
2.7.1 Statement		2.7		
2.7.2 Solution			2.7.2 Solution	

1. Notes.

Chapter IV notes and problems for [1].

There's a lot of magic related to the spherical Harmonics in this chapter, with identities pulled out of the Author's butt. It would be nice to work through that, but need a better reference to work from (or skip ahead to chapter 26 where some of this is apparently derived).

Other stuff pending background derivation and verification are

1.1. Antisymmetric tensor summation identity.

$$\sum_{i} \epsilon_{ijk} \epsilon_{iab} = \delta_{ja} \delta_{kb} - \delta_{jb} \delta_{ka} \tag{1}$$

This is obviously the coordinate equivalent of the dot product of two bivectors

$$(\mathbf{e}_{j} \wedge \mathbf{e}_{k}) \cdot (\mathbf{e}_{a} \wedge \mathbf{e}_{b}) = ((\mathbf{e}_{j} \wedge \mathbf{e}_{k}) \cdot \mathbf{e}_{a}) \cdot \mathbf{e}_{b}) = \delta_{ka}\delta_{jb} - \delta_{ja}\delta_{kb}$$
(2)

We can prove 1 by expanding the LHS of 2 in coordinates

$$(\mathbf{e}_{j} \wedge \mathbf{e}_{k}) \cdot (\mathbf{e}_{a} \wedge \mathbf{e}_{b}) = \sum_{ie} \left\langle \epsilon_{ijk} \mathbf{e}_{j} \mathbf{e}_{k} \epsilon_{eab} \mathbf{e}_{a} \mathbf{e}_{b} \right\rangle$$

$$= \sum_{ie} \epsilon_{ijk} \epsilon_{eab} \left\langle (\mathbf{e}_{i} \mathbf{e}_{i}) \mathbf{e}_{j} \mathbf{e}_{k} (\mathbf{e}_{e} \mathbf{e}_{e}) \mathbf{e}_{a} \mathbf{e}_{b} \right\rangle$$

$$= \sum_{ie} \epsilon_{ijk} \epsilon_{eab} \left\langle \mathbf{e}_{i} \mathbf{e}_{e} I^{2} \right\rangle$$

$$= -\sum_{ie} \epsilon_{ijk} \epsilon_{eab} \delta_{ie}$$

$$= -\sum_{i} \epsilon_{ijk} \epsilon_{iab} \qquad \Box$$

1.2. Question on raising and lowering arguments.

How equation (4.240) was arrived at is not clear. In (4.239) he writes

$$\int_0^{2\pi} \int_0^{\pi} d\theta d\phi (L_- Y_{lm})^{\dagger} L_- Y_{lm} \sin \theta$$

Shouldn't that Hermitian conjugation be just complex conjugation? if so one would have

$$\int_0^{2\pi} \int_0^{\pi} d\theta d\phi L_-^* Y_{lm}^* L_- Y_{lm} \sin \theta$$

How does he end up with the L_{-} and the Y_{lm}^{*} interchanged. What justifies this commutation? A much clearer discussion of this can be found in The operators L_{\pm} , where Dirac notation is used for the normalization discussion.

1.2.1 Vatche's explaination.

Asked Vatche about this and had it explained nicely. He also used the braket notation, and wrote

$$\langle \theta, \phi | l, m \rangle \equiv Y_{lm}(\theta, \phi) \tag{3}$$

and introduces the identity

$$I = \int_0^{\pi} d\theta \sin\theta \int_0^{2\pi} d\phi |\theta, \phi\rangle \langle \theta, \phi| \tag{4}$$

Now, if we want to normalize the state $L_{-}|l,m\rangle$ we write

$$\begin{split} \langle l,m|L_{-}^{\dagger}L_{-}|l,m\rangle &= \langle l,m|L_{-}^{\dagger}L_{-}|l,m\rangle \\ &= \int_{0}^{\pi}d\theta\sin\theta\int_{0}^{2\pi}d\phi\int_{0}^{\pi}d\theta'\sin\theta'\int_{0}^{2\pi}d\phi'\left\langle l,m|\theta,\phi\right\rangle\left\langle \theta,\phi|L_{+}L_{-}|\theta',\phi'\right\rangle\left\langle \theta',\phi'|l,m\right\rangle \\ &= \int_{0}^{\pi}d\theta\sin\theta\int_{0}^{2\pi}d\phi\int_{0}^{\pi}d\theta'\sin\theta'\int_{0}^{2\pi}d\phi'Y_{lm}^{*}(\theta,\phi)\langle\theta,\phi|L_{+}L_{-}|\theta',\phi'\rangleY_{lm}(\theta',\phi') \end{split}$$

Now he points out that the matrix element has both the differential operator portion, as well as a delta function portion, so we would have

$$\langle \theta, \phi | L_+ L_- | \theta', \phi' \rangle = \frac{1}{\sin \theta} \delta(\theta - \theta') \delta(\phi - \phi') L_+(\theta, \phi) L_-(\theta, \phi)$$

where the raising and lowering operators are now in thier differential form

$$L_{+}(\theta,\phi)L_{-}(\theta,\phi) = \hbar e^{i\theta} \left(\partial_{\theta} + i\cot\theta\partial_{\phi}\right) \hbar e^{-i\theta} \left(-\partial_{\theta} + i\cot\theta\partial_{\phi}\right)$$

This now gives us

$$\langle l, m | L_{-}^{\dagger} L_{-} | l, m \rangle = \int_{0}^{\pi} d\theta \int_{0}^{2\pi} d\phi \int_{0}^{\pi} d\theta' \sin \theta' \int_{0}^{2\pi} d\phi' Y_{lm}^{*}(\theta, \phi) L_{+}(\theta, \phi) L_{-}(\theta, \phi) Y_{lm}(\theta', \phi') \delta(\theta - \theta') \delta(\phi - \phi')$$

$$= \int_{0}^{\pi} d\theta \sin \theta \int_{0}^{2\pi} d\phi Y_{lm}^{*}(\theta, \phi) L_{+}(\theta, \phi) L_{-}(\theta, \phi) Y_{lm}(\theta, \phi)$$

This now fills in the reasoning (and notational) gap that the text has between (4.239) and (4.240). It is now clear that in 4.239 (where Hermitian conjugation seemed out of place), that it should just have been regular complex number conjugation. In the context of the normalization integral, Hermitian conjugation plays no role. Here the L_-Y_{lm} used in the text are just functions.

1.3. Another question on raising and lowering arguments.

The reasoning leading to (4.238) isn't clear to me. I fail to see how the L_{-} commutation with L^{2} implies this?

2. Problems

2.1. **Problem 1.**

2.1.1 Statement.

Write down the free particle Schrödinger equation for two dimensions in (i) Cartesian and (ii) polar coordinates. Obtain the corresponding wavefunction.

2.1.2 Cartesian case.

For the Cartesian coordinates case we have

$$H = -\frac{\hbar^2}{2m}(\partial_{xx} + \partial_{yy}) = i\hbar\partial_t \tag{5}$$

Application of separation of variables with $\Psi = XYT$ gives

$$-\frac{\hbar^2}{2m}\left(\frac{X''}{X} + \frac{Y''}{Y}\right) = i\hbar\frac{T'}{T} = E. \tag{6}$$

Immediately, we have the time dependence

$$T \propto e^{-iEt/\hbar},$$
 (7)

with the PDE reduced to

$$\frac{X''}{X} + \frac{Y''}{Y} = -\frac{2mE}{\hbar^2}.\tag{8}$$

Introducing separate independent constants

$$\frac{X''}{X} = a^2 \tag{9}$$

$$\frac{Y''}{Y} = b^2 \tag{10}$$

$$\frac{Y''}{V} = b^2 \tag{10}$$

provides the pre-normalized wave function and the constraints on the constants

$$\Psi = Ce^{ax}e^{by}e^{-iEt/\hbar} \tag{11}$$

$$a^2 + b^2 = -\frac{2mE}{\hbar^2}. (12)$$

2.1.3 Rectangular normalization.

We are now ready to apply normalization constraints. One possibility is a rectangular periodicity requirement.

$$e^{ax} = e^{a(x+\lambda_x)} \tag{13}$$

$$e^{ay} = e^{a(y+\lambda_y)},\tag{14}$$

or

$$a\lambda_x = 2\pi i m \tag{15}$$

$$a\lambda_{\nu} = 2\pi i n. \tag{16}$$

This provides a more explicit form for the energy expression

$$E_{mn} = \frac{1}{2m} 4\pi^2 \hbar^2 \left(\frac{m^2}{\lambda_x^2} + \frac{n^2}{\lambda_y^2} \right). \tag{17}$$

We can also add in the area normalization using

$$\langle \psi | \phi \rangle = \int_{x=0}^{\lambda_x} dx \int_{y=0}^{\lambda_x} dy \psi^*(x, y) \phi(x, y). \tag{18}$$

Our eigenfunctions are now completely specified

$$u_{mn}(x,y,t) = \frac{1}{\sqrt{\lambda_x \lambda_y}} e^{2\pi i x/\lambda_x} e^{2\pi i y/\lambda_y} e^{-iEt/\hbar}.$$
 (19)

The interesting thing about this solution is that we can make arbitrary linear combinations

$$f(x,y) = a_{mn}u_{mn} \tag{20}$$

and then "solve" for a_{mn} , for an arbitrary f(x,y) by taking inner products

$$a_{mn} = \langle u_m n | f \rangle = \int_{x=0}^{\lambda_x} dx \int_{y=0}^{\lambda_x} dy f(x, y) u_m n^*(x, y). \tag{21}$$

This gives the appearance that any function f(x,y) is a solution, but the equality of 20 only applies for functions in the span of this function vector space. The procedure works for arbitrary square integrable functions f(x,y), but the equality really means that the RHS will be the periodic extension of f(x,y).

2.1.4 Infinite space normalization.

An alternate normalization is possible by using the Fourier transform normalization, in which we substitute

$$\frac{2\pi m}{\lambda_x} = k_x \tag{22}$$

$$\frac{2\pi m}{\lambda_x} = k_x$$

$$\frac{2\pi n}{\lambda_y} = k_y$$
(22)

Our inner product is now

$$\langle \psi | \phi \rangle = \int_{-\infty}^{\infty} dx \int_{\infty}^{\infty} dy \psi^*(x, y) \phi(x, y). \tag{24}$$

And the corresponding normalized wavefunction and associated energy constant *E* are

$$u_{\mathbf{k}}(x,y,t) = \frac{1}{2\pi} e^{ik_x x} e^{ik_y y} e^{-iEt/\hbar} = \frac{1}{2\pi} e^{i\mathbf{k}\cdot\mathbf{x}} e^{-iEt/\hbar}$$
(25)

$$E = \frac{\hbar^2 \mathbf{k}^2}{2m} \tag{26}$$

Now via this Fourier inner product we are able to construct a solution from any square integrable function. Again, this will not be an exact equality since the Fourier transform has the effect of averaging across discontinuities.

2.1.5 Polar case.

In polar coordinates our gradient is

$$\nabla = \hat{\mathbf{r}}\partial_r + \frac{\hat{\boldsymbol{\theta}}}{r}\partial_{\boldsymbol{\theta}}.\tag{27}$$

with

$$\hat{\mathbf{r}} = \mathbf{e}_1 e^{\mathbf{e}_1 \mathbf{e}_2 \theta} \tag{28}$$

$$\hat{\boldsymbol{\theta}} = \mathbf{e}_2 e^{\mathbf{e}_1 \mathbf{e}_2 \theta}. \tag{29}$$

Squaring the gradient for the Laplacian we'll need the partials, which are

$$\begin{aligned}
\partial_r \hat{\mathbf{r}} &= 0 \\
\partial_r \hat{\boldsymbol{\theta}} &= 0 \\
\partial_{\theta} \hat{\mathbf{r}} &= \hat{\boldsymbol{\theta}} \\
\partial_{\theta} \hat{\boldsymbol{\theta}} &= -\hat{\mathbf{r}}.
\end{aligned}$$

The Laplacian is therefore

$$\begin{split} \boldsymbol{\nabla}^2 &= (\hat{\mathbf{r}}\partial_r + \frac{\hat{\boldsymbol{\theta}}}{r}\partial_{\theta}) \cdot (\hat{\mathbf{r}}\partial_r + \frac{\hat{\boldsymbol{\theta}}}{r}\partial_{\theta}) \\ &= \partial_{rr} + \frac{\hat{\boldsymbol{\theta}}}{r} \cdot \partial_{\theta}\hat{\mathbf{r}}\partial_r \frac{\hat{\boldsymbol{\theta}}}{r} \cdot \partial_{\theta} \frac{\hat{\boldsymbol{\theta}}}{r}\partial_{\theta} \\ &= \partial_{rr} + \frac{\hat{\boldsymbol{\theta}}}{r} \cdot (\partial_{\theta}\hat{\mathbf{r}})\partial_r + \frac{\hat{\boldsymbol{\theta}}}{r} \cdot \frac{\hat{\boldsymbol{\theta}}}{r}\partial_{\theta\theta} + \frac{\hat{\boldsymbol{\theta}}}{r} \cdot (\partial_{\theta}\hat{\boldsymbol{\theta}}) \frac{1}{r}\partial_{\theta}. \end{split}$$

Evalating the derivatives we have

$$\nabla^2 = \partial_{rr} + \frac{1}{r}\partial_r + \frac{1}{r^2}\partial_{\theta\theta},\tag{30}$$

and are now prepared to move on to the solution of the Hamiltonian $H=-(\hbar^2/2m)\nabla^2$. With separation of variables again using $\Psi=R(r)\Theta(\theta)T(t)$ we have

$$-\frac{\hbar^2}{2m}\left(\frac{R''}{R} + \frac{R'}{rR} + \frac{1}{r^2}\frac{\Theta''}{\Theta}\right) = i\hbar\frac{T'}{T} = E.$$
(31)

Rearranging to separate the Θ term we have

$$\frac{r^2R''}{R} + \frac{rR'}{R} + \frac{2mE}{\hbar^2}r^2E = -\frac{\Theta''}{\Theta} = \lambda^2.$$
 (32)

The angular solutions are given by

$$\Theta = \frac{1}{\sqrt{2\pi}} e^{i\lambda\theta} \tag{33}$$

Where the normalization is given by

$$\langle \psi | \phi \rangle = \int_0^{2\pi} d\theta \psi^*(\theta) \phi(\theta). \tag{34}$$

And the radial by the solution of the PDE

$$r^{2}R'' + rR' + \left(\frac{2mE}{\hbar^{2}}r^{2}E - \lambda^{2}\right)R = 0$$
 (35)

2.2. **Problem 2.**

2.2.1 Statement.

Use the orthogonality property of $P_l(\cos \theta)$

$$\int_{-1}^{1} dx P_{l}(x) P_{l'}(x) = \frac{2}{2l+1} \delta_{ll'}, \tag{36}$$

confirm that at least the first two terms of (4.171)

$$e^{ikr\cos\theta} = \sum_{l=0}^{\infty} (2l+1)i^l j_l(kr) P_l(\cos\theta)$$
(37)

are correct.

2.2.2 Solution.

Taking the inner product using the integral of 36 we have

$$\int_{-1}^{1} dx e^{ikrx} P_l'(x) = 2i^l j_l(kr)$$
 (38)

To confirm the first two terms we need

$$P_0(x) = 1 \tag{39}$$

$$P_1(x) = x \tag{40}$$

$$j_0(\rho) = \frac{\sin \rho}{\rho} \tag{41}$$

$$j_1(\rho) = \frac{\sin \rho}{\rho^2} - \frac{\cos \rho}{\rho}.$$
 (42)

On the LHS for l' = 0 we have

$$\int_{-1}^{1} dx e^{ikrx} = 2 \frac{\sin kr}{kr} \tag{43}$$

On the LHS for l' = 1 note that

$$\int dx x e^{ikrx} = \int dx x \frac{d}{dx} \frac{e^{ikrx}}{ikr}$$
$$= x \frac{e^{ikrx}}{ikr} - \frac{e^{ikrx}}{(ikr)^2}.$$

So, integration in [-1,1] gives us

$$\int_{-1}^{1} dx e^{ikrx} = -2i \frac{\cos kr}{kr} + 2i \frac{1}{(kr)^2} \sin kr.$$
 (44)

Now compare to the RHS for l' = 0, which is

$$2j_0(kr) = 2\frac{\sin kr}{kr},\tag{45}$$

which matches 43. For l' = 1 we have

$$2ij_1(kr) = 2i\frac{1}{kr} \left(\frac{\sin kr}{kr} - \cos kr \right), \tag{46}$$

which in turn matches 44, completing the exersize.

2.3. **Problem 3.**

2.3.1 Statement.

Obtain the commutation relations $[L_i, L_j]$ by calculating the vector $\mathbf{L} \times \mathbf{L}$ using the definition $\mathbf{L} = \mathbf{r} \times \mathbf{p}$ directly instead of introducing a differential operator.

2.3.2 Solution.

Expressing the product $L \times L$ in determinant form sheds some light on this question. That is

$$\begin{vmatrix} \mathbf{e}_{1} & \mathbf{e}_{2} & \mathbf{e}_{3} \\ L_{1} & L_{2} & L_{3} \\ L_{1} & L_{2} & L_{3} \end{vmatrix} = \mathbf{e}_{1} [L_{2}, L_{3}] + \mathbf{e}_{2} [L_{3}, L_{1}] + \mathbf{e}_{3} [L_{1}, L_{2}] = \mathbf{e}_{i} \epsilon_{ijk} [L_{j}, L_{k}]$$

$$(47)$$

We see that evaluating this cross product in turn requires evaluation of the set of commutators. We can do that with the canonical commutator relationships directly using $L_i = \epsilon_{ijk} r_j p_k$ like so

$$\begin{split} \left[L_{i},L_{j}\right] &= \epsilon_{imn}r_{m}p_{n}\epsilon_{jab}r_{a}p_{b} - \epsilon_{jab}r_{a}p_{b}\epsilon_{imn}r_{m}p_{n} \\ &= \epsilon_{imn}\epsilon_{jab}r_{m}(p_{n}r_{a})p_{b} - \epsilon_{jab}\epsilon_{imn}r_{a}(p_{b}r_{m})p_{n} \\ &= \epsilon_{imn}\epsilon_{jab}r_{m}(r_{a}p_{n} - i\hbar\delta_{an})p_{b} - \epsilon_{jab}\epsilon_{imn}r_{a}(r_{m}p_{b} - i\hbar\delta mb)p_{n} \\ &= \epsilon_{imn}\epsilon_{jab}(r_{m}r_{a}p_{n}p_{b} - r_{a}r_{m}p_{b}p_{n}) - i\hbar(\epsilon_{imn}\epsilon_{jnb}r_{m}p_{b} - \epsilon_{jam}\epsilon_{imn}r_{a}p_{n}). \end{split}$$

The first two terms cancel, and we can employ (4.179) to eliminate the antisymmetric tensors from the last two terms

$$\begin{split} \left[L_{i},L_{j}\right] &= i\hbar(\epsilon_{nim}\epsilon_{njb}r_{m}p_{b} - \epsilon_{mja}\epsilon_{min}r_{a}p_{n}) \\ &= i\hbar((\delta_{ij}\delta_{mb} - \delta_{ib}\delta_{mj})r_{m}p_{b} - (\delta_{ji}\delta_{an} - \delta_{jn}\delta_{ai})r_{a}p_{n}) \\ &= i\hbar(\delta_{ij}\delta_{mb}r_{m}p_{b} - \delta_{ji}\delta_{an}r_{a}p_{n} - \delta_{ib}\delta_{mj}r_{m}p_{b} + \delta_{jn}\delta_{ai}r_{a}p_{n}) \\ &= i\hbar(\delta_{ij}r_{m}p_{m} - \delta_{ji}r_{a}p_{a} - r_{j}p_{i} + r_{i}p_{j}) \end{split}$$

For $k \neq i, j$, this is $i\hbar(\mathbf{r} \times \mathbf{p})_k$, so we can write

$$\mathbf{L} \times \mathbf{L} = i\hbar \mathbf{e}_k \epsilon_{kij} (r_i p_j - r_j p_i) = i\hbar \mathbf{L} = i\hbar \mathbf{e}_k L_k = i\hbar \mathbf{L}. \tag{48}$$

In [2], the commutator relationships are summarized this way, instead of using the antisymmetric tensor (4.224)

$$[L_i, L_j] = i\hbar \epsilon_{ijk} L_k \tag{49}$$

as here in Desai. Both say the same thing.

2.4. Problem 4.

2.4.1 Statement.

2.4.2 Solution.

TODO.

2.5. **Problem 5.**

2.5.1 Statement.

A free particle is moving along a path of radius *R*. Express the Hamiltonian in terms of the derivatives involving the polar angle of the particle and write down the Schrödinger equation. Determine the wavefunction and the energy eigenvalues of the particle.

2.5.2 Solution.

In classical mechanics our Lagrangian for this system is

$$\mathcal{L} = \frac{1}{2}mR^2\dot{\theta}^2,\tag{50}$$

with the canonical momentum

$$p_{\theta} = \frac{\partial \mathcal{L}}{\partial \dot{\theta}} = mR^2 \dot{\theta}. \tag{51}$$

Thus the classical Hamiltonian is

$$H = \frac{1}{2mR^2} p_{\theta}^2. {(52)}$$

By analogy the QM Hamiltonian operator will therefore be

$$H = -\frac{\hbar^2}{2mR^2} \partial_{\theta\theta}. \tag{53}$$

For $\Psi = \Theta(\theta)T(t)$, separation of variables gives us

$$-\frac{\hbar^2}{2mR^2}\frac{\Theta''}{\Theta} = i\hbar \frac{T'}{T} = E,$$
(54)

from which we have

$$T \propto e^{-iEt/\hbar} \tag{55}$$

$$\Theta \propto e^{\pm i\sqrt{2mE}R\theta/\hbar}.$$
 (56)

Requiring single valued Θ , equal at any multiples of 2π , we have

$$e^{\pm i\sqrt{2mE}R(\theta+2\pi)/\hbar} = e^{\pm i\sqrt{2mE}R\theta/\hbar}$$

or

$$\pm\sqrt{2mE}\frac{R}{\hbar}2\pi=2\pi n,$$

Suffixing the energy values with this index we have

$$E_n = \frac{n^2 \hbar^2}{2mR^2}. (57)$$

Allowing both positive and negative integer values for n we have

$$\Psi = \frac{1}{\sqrt{2\pi}} e^{in\theta} e^{-iE_n t/\hbar},\tag{58}$$

where the normalization was a result of the use of a $[0,2\pi]$ inner product over the angles

$$\langle \psi | \phi \rangle \equiv \int_0^{2\pi} \psi^*(\theta) \phi(\theta) d\theta.$$
 (59)

2.6. Problem 6.

2.6.1 Statement.

Determine $[L_i, r]$ and $[L_i, \mathbf{r}]$.

2.6.2 Solution.

Since L_i contain only θ and ϕ partials, $[L_i, r] = 0$. For the position vector, however, we have an angular dependence, and are left to evaluate $[L_i, \mathbf{r}] = r[L_i, \hat{\mathbf{r}}]$. We'll need the partials for $\hat{\mathbf{r}}$. We have

$$\hat{\mathbf{r}} = \mathbf{e}_3 e^{I\hat{\boldsymbol{\phi}}\theta} \tag{60}$$

$$\hat{\boldsymbol{\phi}} = \mathbf{e}_2 e^{\mathbf{e}_1 \mathbf{e}_2 \phi} \tag{61}$$

$$I = \mathbf{e}_1 \mathbf{e}_2 \mathbf{e}_3 \tag{62}$$

Evaluating the partials we have

$$\partial_{\theta}\hat{\mathbf{r}} = \hat{\mathbf{r}}I\hat{\boldsymbol{\phi}}$$

With

$$\hat{\boldsymbol{\theta}} = \tilde{R}\mathbf{e}_1 R \tag{63}$$

$$\hat{\boldsymbol{\phi}} = \tilde{R}\mathbf{e}_2 R \tag{64}$$

$$\hat{\mathbf{r}} = \tilde{R}\mathbf{e}_3 R \tag{65}$$

where $\tilde{R}R = 1$, and $\hat{\boldsymbol{\theta}}\hat{\boldsymbol{\phi}}\hat{\mathbf{r}} = \mathbf{e}_1\mathbf{e}_2\mathbf{e}_3$, we have

$$\partial_{\theta}\hat{\mathbf{r}} = \tilde{R}\mathbf{e}_{3}\mathbf{e}_{1}\mathbf{e}_{2}\mathbf{e}_{3}\mathbf{e}_{2}R = \tilde{R}\mathbf{e}_{1}R = \hat{\boldsymbol{\theta}}$$

$$\tag{66}$$

For the ϕ partial we have

$$\partial_{\phi} \hat{\mathbf{r}} = \mathbf{e}_3 \sin \theta I \hat{\boldsymbol{\phi}} \mathbf{e}_1 \mathbf{e}_2$$
$$= \sin \theta \hat{\boldsymbol{\phi}}$$

We are now prepared to evaluate the commutators. Starting with the easiest we have

$$[L_z, \hat{\mathbf{r}}] \Psi = -i\hbar(\partial_{\phi}\hat{\mathbf{r}}\Psi - \hat{\mathbf{r}}\partial_{\phi}\Psi)$$
$$= -i\hbar(\partial_{\phi}\hat{\mathbf{r}})\Psi$$

So we have

$$[L_z, \hat{\mathbf{r}}] = -i\hbar \sin\theta \hat{\boldsymbol{\phi}} \tag{67}$$

Observe that by virtue of chain rule, only the action of the partials on $\hat{\mathbf{r}}$ itself contributes, and all the partials applied to Ψ cancel out due to the commutator differences. That simplifies the remaining commutator evaluations. For reference the polar form of L_x , and L_y are

$$L_x = -i\hbar(-S_\phi \partial_\theta - C_\phi \cot \theta \partial_\phi) \tag{68}$$

$$L_{y} = -i\hbar(C_{\phi}\partial_{\theta} - S_{\phi}\cot\theta\partial_{\phi}), \tag{69}$$

where the sines and cosines are written with *S*, and *C* respectively for short. We therefore have

$$[L_x, \hat{\mathbf{r}}] = -i\hbar(-S_{\phi}(\partial_{\theta}\hat{\mathbf{r}}) - C_{\phi}\cot\theta(\partial_{\phi}\hat{\mathbf{r}}))$$

= $-i\hbar(-S_{\phi}\hat{\boldsymbol{\theta}} - C_{\phi}\cot\theta S_{\theta}\hat{\boldsymbol{\phi}})$
= $-i\hbar(-S_{\phi}\hat{\boldsymbol{\theta}} - C_{\phi}C_{\theta}\hat{\boldsymbol{\phi}})$

and

$$[L_{y}, \hat{\mathbf{r}}] = -i\hbar(C_{\phi}(\partial_{\theta}\hat{\mathbf{r}}) - S_{\phi}\cot\theta(\partial_{\phi}\hat{\mathbf{r}}))$$

= $-i\hbar(C_{\phi}\hat{\boldsymbol{\theta}} - S_{\phi}C_{\theta}\hat{\boldsymbol{\phi}}).$

Adding back in the factor of *r*, and summarizing we have

$$[L_i, r] = 0 (70)$$

$$[L_x, \mathbf{r}] = -i\hbar r(-\sin\phi\hat{\boldsymbol{\theta}} - \cos\phi\cos\phi\hat{\boldsymbol{\phi}}) \tag{71}$$

$$[L_{y}, \mathbf{r}] = -i\hbar r(\cos\phi\hat{\boldsymbol{\theta}} - \sin\phi\cos\theta\hat{\boldsymbol{\phi}}) \tag{72}$$

$$[L_z, \mathbf{r}] = -i\hbar r \sin\theta \hat{\boldsymbol{\phi}} \tag{73}$$

2.7. **Problem 7.**

2.7.1 Statement.

Show that

$$e^{-i\pi L_x/\hbar}|l,m\rangle = |l,m-1\rangle$$
 (74)

2.7.2 Solution.

TODO.

References

- [1] BR Desai. Quantum mechanics with basic field theory. Cambridge University Press, 2009. 1
- [2] R. Liboff. Introductory quantum mechanics. 2003. 2.3.2