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**ECE1254H Modeling of Multiphysics Systems. Lecture 6: Singular value decomposition, and conditioning number. Taught by Prof. Piero Triverio**

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1.1 Disclaimer

Peeter's lecture notes from class. These may be incoherent and rough.

1.2 Matrix norm

We've defined the matrix norm of  $M$ , for the system  $\bar{y} = M\bar{x}$  as

$$\|M\| = \max_{\|\bar{x}\|=1} \|M\bar{x}\|. \quad (1.1)$$

We will typically use the  $L_2$  norm, so that the matrix norm is

$$\|M\|_2 = \max_{\|\bar{x}\|_2=1} \|M\bar{x}\|_2. \quad (1.2)$$

It can be shown that

$$\|M\|_2 = \max_i \sigma_i(M), \quad (1.3)$$

where  $\sigma_i(M)$  are the (SVD) singular values.

**Definition 1.1: Singular value decomposition (SVD)**

Given  $M \in \mathbb{R}^{m \times n}$ , we can find a representation of  $M$

$$M = U\Sigma V^T, \quad (1.4)$$

where  $U$  and  $V$  are orthogonal matrices such that  $U^T U = 1$ , and  $V^T V = 1$ , and

$$\Sigma = \begin{bmatrix} \sigma_1 & & & & & \\ & \sigma_2 & & & & \\ & & \ddots & & & \\ & & & \sigma_r & & \\ & & & & 0 & \\ & & & & & \ddots \\ & & & & & & 0 \end{bmatrix} \quad (1.5)$$

The values  $\sigma_i, i \leq \min(n, m)$  are called the singular values of  $M$ . The singular values are subject to the ordering

$$\sigma_1 \geq \sigma_2 \geq \dots \geq 0 \quad (1.6)$$

If  $r$  is the rank of  $M$ , then the  $\sigma_r$  above is the minimum non-zero singular value (but the zeros are also called singular values).

Observe that the condition  $U^T U = 1$  is a statement of orthonormality. In terms of column vectors  $\bar{u}_i$ , such a product written out explicitly is

$$\begin{bmatrix} \bar{u}_1^T \\ \bar{u}_2^T \\ \vdots \\ \bar{u}_m^T \end{bmatrix} [\bar{u}_1 \quad \bar{u}_2 \quad \dots \quad \bar{u}_m] = \begin{bmatrix} 1 & & & \\ & 1 & & \\ & & \ddots & \\ & & & 1 \end{bmatrix}. \quad (1.7)$$

This is both normality  $\bar{u}_i^T \bar{u}_i = 1$ , and orthonormality  $\bar{u}_i^T \bar{u}_j = 0, i \neq j$ .

### Example 1.1: 2 x 2 case

(for column vectors  $\bar{u}_i, \bar{v}_j$ ).

$$M = [\bar{u}_1 \quad \bar{u}_2] \begin{bmatrix} \sigma_1 & \\ & \sigma_2 \end{bmatrix} \begin{bmatrix} \bar{v}_1^T \\ \bar{v}_2^T \end{bmatrix} \quad (1.8)$$

Consider  $\bar{y} = M\bar{x}$ , and take an  $\bar{x}$  with  $\|\bar{x}\|_2 = 1$

Note: I've chosen not to sketch what was drawn on the board. See instead the animated gif of the same in [? ].

### 1.3 Conditioning number

Given a perturbation of  $M\bar{x} = \bar{b}$  to

$$(M + \delta M)(\bar{x} + \delta \bar{x}) = \bar{b}, \quad (1.9)$$

or

$$M\bar{x} - \vec{b} + \delta M\bar{x} + M\delta\bar{x} + \delta M\delta\bar{x} = 0. \tag{1.10}$$

This gives

$$M\delta\bar{x} = -\delta M\bar{x} - \delta M\delta\bar{x}, \tag{1.11}$$

or

$$\delta\bar{x} = -M^{-1}\delta M(\bar{x} + \delta\bar{x}). \tag{1.12}$$

Taking norms

$$\begin{aligned} \|\delta\bar{x}\|_2 &= \left\| M^{-1}\delta M(\bar{x} + \delta\bar{x}) \right\|_2 \\ &\leq \left\| M^{-1} \right\|_2 \|\delta M\|_2 \|\bar{x} + \delta\bar{x}\|_2, \end{aligned} \tag{1.13}$$

or

relative error of solution

$$\frac{\|\delta\bar{x}\|_2}{\|\bar{x} + \delta\bar{x}\|_2} \leq \underbrace{\|M\|_2 \|M^{-1}\|_2}_{\text{conditioning number of } M} \underbrace{\frac{\|\delta M\|_2}{\|M\|_2}}_{\text{relative perturbation of } M}. \tag{1.14}$$

The conditioning number can be shown to be

$$\text{cond}(M) = \frac{\sigma_{\max}}{\sigma_{\min}} \geq 1 \tag{1.15}$$

FIXME: justify.

### 1.3.1 sensitivity to conditioning number

Double precision relative rounding errors can be of the order  $10^{-16} \sim 2^{-54}$ , which allows us to gauge the relative error of the solution

relative error of solution	$\leq$	cond(M)	$\frac{\ \delta M\ }{\ M\ }$
$10^{-15}$	$\leq$	10	$\sim 10^{-16}$
$10^{-2}$	$\leq$	$10^{14}$	$10^{-16}$