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## Unpacking the fundamental theorem in two dimensions.

Given a two dimensional generating vector space, there are two instances of the fundamental theorem for multivector integration

$$
\begin{equation*}
\int_{S} F d \mathbf{x} \stackrel{\leftrightarrow}{\partial} G=\left.F G\right|_{\Delta S} \tag{1.1}
\end{equation*}
$$

and

$$
\begin{equation*}
\int_{S} F d^{2} \mathbf{x} \stackrel{\leftrightarrow}{\partial} G=\oint_{\partial S} F d \mathbf{x} G \tag{1.2}
\end{equation*}
$$

The first case is trivial. Given a parameterizated curve $x=x(u)$, it just states

$$
\begin{equation*}
\int_{u(0)}^{u(1)} d u \frac{\partial}{\partial u}(F G)=F(u(1)) G(u(1))-F(u(0)) G(u(0)), \tag{1.3}
\end{equation*}
$$

for all multivectors $F, G$, regardless of the signature of the underlying space.
The surface integral is more interesting. Let's first look at the area element for this surface integral, which is

$$
\begin{equation*}
d^{2} \mathbf{x}=d \mathbf{x}_{u} \wedge d \mathbf{x}_{v} . \tag{1.4}
\end{equation*}
$$

Geometrically, this has the area of the parallelogram spanned by $d \mathbf{x}_{u}$ and $d \mathbf{x}_{v}$, but weighted by the pseudoscalar of the space. This is explored algebraically in exercise 1.1 and illustrated in fig. 1.1.

Exercise 1.1 Expansion of 2D area bivector.
Let $\left\{e_{1}, e_{2}\right\}$ be an orthonormal basis for a two dimensional space, with reciprocal frame $\left\{e^{1}, e^{2}\right\}$. Expand the area bivector $d^{2} \mathbf{x}$ in coordinates relating the bivector to the Jacobian and the pseudoscalar.
Answer for Exercise 1.1
With parameterization $x=x(u, v)=x^{\alpha} e_{\alpha}=x_{\alpha} e^{\alpha}$, we have

$$
\begin{align*}
\mathbf{x}_{u} \wedge \mathbf{x}_{v} & =\left(\frac{\partial x^{\alpha}}{\partial u} e_{\alpha}\right) \wedge\left(\frac{\partial x^{\beta}}{\partial v} e_{\beta}\right) \\
& =\frac{\partial x^{\alpha}}{\partial u} \frac{\partial x^{\beta}}{\partial v} e_{\alpha} e_{\beta}  \tag{1.5}\\
& =\frac{\partial\left(x^{1}, x^{2}\right)}{\partial(u, v)} e_{1} e_{2},
\end{align*}
$$



Figure 1.1: 2D vector space and area element.
or

$$
\begin{align*}
\mathbf{x}_{u} \wedge \mathbf{x}_{v} & =\left(\frac{\partial x_{\alpha}}{\partial u} e^{\alpha}\right) \wedge\left(\frac{\partial x_{\beta}}{\partial v} e^{\beta}\right) \\
& =\frac{\partial x_{\alpha}}{\partial u} \frac{\partial x_{\beta}}{\partial v} e^{\alpha} e^{\beta}  \tag{1.6}\\
& =\frac{\partial\left(x_{1}, x_{2}\right)}{\partial(u, v)} e^{1} e^{2} .
\end{align*}
$$

The upper and lower index pseudoscalars are related by

$$
\begin{equation*}
e^{1} e^{2} e_{1} e_{2}=-e^{1} e^{2} e_{2} e_{1}=-1 \text {, } \tag{1.7}
\end{equation*}
$$

so with $I=e_{1} e_{2}$,

$$
\begin{equation*}
e^{1} e^{2}=-I^{-1} \tag{1.8}
\end{equation*}
$$

leaving us with

$$
\begin{equation*}
d^{2} \mathbf{x}=\frac{\partial\left(x^{1}, x^{2}\right)}{\partial(u, v)} d u d v I=-\frac{\partial\left(x_{1}, x_{2}\right)}{\partial(u, v)} d u d v I^{-1} . \tag{1.9}
\end{equation*}
$$

We see that the area bivector is proportional to either the upper or lower index Jacobian and to the pseudoscalar for the space.

We may write the fundamental theorem for a 2D space as

$$
\begin{equation*}
\int_{S} d u d v \frac{\partial\left(x^{1}, x^{2}\right)}{\partial(u, v)} F I \stackrel{\leftrightarrow}{\nabla} G=\oint_{\partial S} F d \mathbf{x} G, \tag{1.10}
\end{equation*}
$$

where we have dispensed with the vector derivative and use the gradient instead, since they are identical in a two parameter two dimensional space. Of course, unless we are using $x^{1}, x^{2}$ as our parameterization, we still want the curvilinear representation of the gradient $\nabla=\mathbf{x}^{u} \partial / \partial u+\mathbf{x}^{v} \partial / \partial v$.

Exercise 1.2 Standard basis expansion of fundamental surface relation.
For a parameterization $x=x^{1} e_{1}+x^{2} e_{2}$, where $\left\{e_{1}, e_{2}\right\}$ is a standard (orthogonal) basis, expand the fundamental theorem for surface integrals for the single sided $F=1$ case. Consider functions $G$ of each grade (scalar, vector, bivector.)
Answer for Exercise 1.2
From exercise 1.1 we see that the fundamental theorem takes the form

$$
\begin{equation*}
\int_{S} d x^{1} d x^{2} F I \stackrel{\leftrightarrow}{\nabla} G=\oint_{\partial S} F d \mathbf{x} G . \tag{1.11}
\end{equation*}
$$

In a Euclidean space, the operator $I \stackrel{\leftrightarrow}{\nabla}$, is a $\pi / 2$ rotation of the gradient, but has a rotated like structure in all metrics:

$$
\begin{equation*}
I \nabla=e_{1} e_{2}\left(e^{1} \partial_{1}+e^{2} \partial_{2}\right)=-e_{2} \partial_{1}+e_{1} \partial_{2} \tag{1.12}
\end{equation*}
$$

- $F=1$ and $G \in \bigwedge^{0}$ or $G \in \bigwedge^{2}$. For $F=1$ and scalar or bivector $G$ we have

$$
\begin{equation*}
\int_{S} d x^{1} d x^{2}\left(-e_{2} \partial_{1}+e_{1} \partial_{2}\right) G=\oint_{\partial S} d \mathbf{x} G \tag{1.13}
\end{equation*}
$$

where, for $x^{1} \in\left[x^{1}(0), x^{1}(1)\right]$ and $x^{2} \in\left[x^{2}(0), x^{2}(1)\right]$, the RHS written explicitly is

$$
\begin{equation*}
\oint_{\partial S} d \mathbf{x} G=\int d x^{1} e_{1}\left(G\left(x^{1}, x^{2}(1)\right)-G\left(x^{1}, x^{2}(0)\right)\right)-d x^{2} e_{2}\left(G\left(x^{1}(1), x^{2}\right)-G\left(x^{1}(0), x^{2}\right)\right) \tag{1.14}
\end{equation*}
$$

This is sketched in fig. 1.2. Since a 2D bivector $G$ can be written as $G=I g$, where $g$ is a scalar, we may write the pseudoscalar case as

$$
\begin{equation*}
\int_{S} d x^{1} d x^{2}\left(-e_{2} \partial_{1}+e_{1} \partial_{2}\right) g=\oint_{\partial S} d \mathbf{x} g \tag{1.15}
\end{equation*}
$$

after right multiplying both sides with $I^{-1}$. Algebraically the scalar and pseudoscalar cases can be thought of as identical scalar relationships.

- $F=1, G \in \Lambda^{1}$. For $F=1$ and vector $G$ the 2 D fundamental theorem for surfaces can be split into scalar

$$
\begin{equation*}
\int_{S} d x^{1} d x^{2}\left(-e_{2} \partial_{1}+e_{1} \partial_{2}\right) \cdot G=\oint_{\partial S} d \mathbf{x} \cdot G \tag{1.16}
\end{equation*}
$$

and bivector relations

$$
\begin{equation*}
\int_{S} d x^{1} d x^{2}\left(-e_{2} \partial_{1}+e_{1} \partial_{2}\right) \wedge G=\oint_{\partial S} d \mathbf{x} \wedge G \tag{1.17}
\end{equation*}
$$

To expand eq. (1.16), let

$$
\begin{equation*}
G=g_{1} e^{1}+g_{2} e^{2} \tag{1.18}
\end{equation*}
$$

for which

$$
\begin{align*}
\left(-e_{2} \partial_{1}+e_{1} \partial_{2}\right) \cdot G & =\left(-e_{2} \partial_{1}+e_{1} \partial_{2}\right) \cdot\left(g_{1} e^{1}+g_{2} e^{2}\right)  \tag{1.19}\\
& =\partial_{2} g_{1}-\partial_{1} g_{2}
\end{align*}
$$

and

$$
\begin{align*}
d \mathbf{x} \cdot G & =\left(d x^{1} e_{1}-d x^{2} e_{2}\right) \cdot\left(g_{1} e^{1}+g_{2} e^{2}\right)  \tag{1.20}\\
& =d x^{1} g_{1}-d x^{2} g_{2}
\end{align*}
$$

so eq. (1.16) expands to

$$
\begin{equation*}
\int_{S} d x^{1} d x^{2}\left(\partial_{2} g_{1}-\partial_{1} g_{2}\right)=\left.\int d x^{1} g_{1}\right|_{\Delta x^{2}}-\left.d x^{2} g_{2}\right|_{\Delta x^{1}} \tag{1.21}
\end{equation*}
$$

This coordinate expansion illustrates how the pseudoscalar nature of the area element results in a duality transformation, as we end up with a curl like operation on the LHS, despite the dot product nature of the decomposition that we used. That can also be seen directly for vector $G$, since

$$
\begin{align*}
d A(I \nabla) \cdot G & =d A\langle I \nabla G\rangle \\
& =d A I(\nabla \wedge G) \tag{1.22}
\end{align*}
$$

since the scalar selection of $I(\nabla \cdot G)$ is zero.
In the grade-2 relation eq. (1.17), we expect a pseudoscalar cancellation on both sides, leaving a scalar (divergence-like) relationship. This time, we use upper index coordinates for the vector $G$, letting

$$
\begin{equation*}
G=g^{1} e_{1}+g^{2} e_{2} \tag{1.23}
\end{equation*}
$$

So

$$
\begin{align*}
\left(-e_{2} \partial_{1}+e_{1} \partial_{2}\right) \wedge G & =\left(-e_{2} \partial_{1}+e_{1} \partial_{2}\right) \wedge G\left(g^{1} e_{1}+g^{2} e_{2}\right)  \tag{1.24}\\
& =e_{1} e_{2}\left(\partial_{1} g^{1}+\partial_{2} g^{2}\right)
\end{align*}
$$

and

$$
\begin{align*}
d \mathbf{x} \wedge G & =\left(d x^{1} e_{1}-d x^{2} e_{2}\right) \wedge\left(g^{1} e_{1}+g^{2} e_{2}\right) \\
& =e_{1} e_{2}\left(d x^{1} g^{2}+d x^{2} g^{1}\right) \tag{1.25}
\end{align*}
$$

So eq. (1.17), after multiplication of both sides by $I^{-1}$, is

$$
\begin{equation*}
\int_{S} d x^{1} d x^{2}\left(\partial_{1} g^{1}+\partial_{2} g^{2}\right)=\left.\int d x^{1} g^{2}\right|_{\Delta x^{2}}+\left.d x^{2} g^{1}\right|_{\Delta x^{1}} \tag{1.26}
\end{equation*}
$$

As before, we've implicitly performed a duality transformation, and end up with a divergence operation. That can be seen directly without coordinate expansion, by rewriting the wedge as a grade two selection, and expanding the gradient action on the vector $G$, as follows

$$
\begin{align*}
d A(I \nabla) \wedge G & =d A\langle I \nabla G\rangle_{2} \\
& =d A I(\nabla \cdot G) \tag{1.27}
\end{align*}
$$

since $I(\nabla \wedge G)$ has only a scalar component.


Figure 1.2: Line integral around rectangular boundary.

## Theorem 1.1: Green's theorem [1].

Let $S$ be a Jordan region with a piecewise-smooth boundary $C$. If $P, Q$ are continuously differentiable on an open set that contains $S$, then

$$
\int d x d y\left(\frac{\partial P}{\partial y}-\frac{\partial Q}{\partial x}\right)=\oint P d x+Q d y
$$

## Exercise 1.3 Relationship to Green's theorem.

If the space is Euclidean, show that eq. (1.21) and eq. (1.26) are both instances of Green's theorem with suitable choices of $P$ and $Q$.
Answer for Exercise 1.3
I will omit the subtleties related to general regions and consider just the case of an infinitesimal square region.
Let's start with eq. (1.21), with $g_{1}=P$ and $g_{2}=Q$, and $x^{1}=x, x^{2}=y$, the RHS is

$$
\begin{equation*}
\int d x d y\left(\frac{\partial P}{\partial y}-\frac{\partial Q}{\partial x}\right) . \tag{1.28}
\end{equation*}
$$

On the RHS we have

$$
\begin{equation*}
\left.\int d x P\right|_{\Delta y}-\left.d y Q\right|_{\Delta x}=\int d x\left(P\left(x, y_{1}\right)-P\left(x, y_{0}\right)\right)-\int d y\left(Q\left(x_{1}, y\right)-Q\left(x_{0}, y\right)\right) \tag{1.29}
\end{equation*}
$$

This pair of integrals is plotted in fig. 1.3, from which we see that eq. (1.29) can be expressed as the line integral, leaving us with

$$
\begin{equation*}
\int d x d y\left(\frac{\partial P}{\partial y}-\frac{\partial Q}{\partial x}\right)=\oint d x P+d y Q \tag{1.30}
\end{equation*}
$$

which is Green's theorem over the infinitesimal square integration region.
For the equivalence of eq. (1.26) to Green's theorem, let $g^{2}=P$, and $g^{1}=-Q$. Plugging into the LHS, we find the Green's theorem integrand. On the RHS, the integrand expands to

$$
\begin{equation*}
\left.d x g^{2}\right|_{\Delta y}+\left.d y g^{1}\right|_{\Delta x}=d x\left(P\left(x, y_{1}\right)-P\left(x, y_{0}\right)\right)+d y\left(-Q\left(x_{1}, y\right)+Q\left(x_{0}, y\right)\right), \tag{1.31}
\end{equation*}
$$

which is exactly what we found in eq. (1.29).


Figure 1.3: Path for Green's theorem.
We may also relate multivector gradient integrals in 2D to the normal integral around the boundary of the bounding curve. That relationship is as follows.

Theorem 1.2: 2D gradient integrals.

$$
\begin{aligned}
& \int J d u d v \vec{\nabla} G=\oint I^{-1} d \mathbf{x} G=\int J\left(\mathbf{x}^{v} d u+\mathbf{x}^{u} d v\right) G \\
& \int J d u d v F \overleftarrow{\nabla}=\oint F I^{-1} d \mathbf{x}=\int J F\left(\mathbf{x}^{v} d u+\mathbf{x}^{u} d v\right),
\end{aligned}
$$

where $J=\partial\left(x^{1}, x^{2}\right) / \partial(u, v)$ is the Jacobian of the parameterization $x=x(u, v)$. In terms of the coordinates $x^{1}, x^{2}$, this reduces to

$$
\begin{aligned}
\int d x^{1} d x^{2} \vec{\nabla} G & =\oint I^{-1} d \mathbf{x} G
\end{aligned}=\int\left(e^{2} d x^{1}+e^{1} d x^{2}\right) G, ~ \begin{aligned}
\int d x^{1} d x^{2} F \overleftarrow{\nabla} & =\oint G I^{-1} d \mathbf{x}
\end{aligned}=\int F\left(e^{2} d x^{1}+e^{1} d x^{2}\right) . ~ \$
$$

The vector $I^{-1} d \mathbf{x}$ is orthogonal to the tangent vector along the boundary, and for Euclidean spaces it can be identified as the outwards normal.

Proof. Respectively setting $F=1$, and $G=1$ in eq. (1.10), we have

$$
\begin{equation*}
\int I^{-1} d^{2} \mathbf{x} \vec{\nabla} G=\oint I^{-1} d \mathbf{x} G \tag{1.32}
\end{equation*}
$$

and

$$
\begin{equation*}
\int F d^{2} \mathbf{x} \stackrel{\leftarrow}{\nabla} I^{-1}=\oint F d \mathbf{x} I^{-1} \tag{1.33}
\end{equation*}
$$

Starting with eq. (1.32) we find

$$
\begin{equation*}
\int I^{-1} J d u d v I \vec{\nabla} G=\oint d \mathbf{x} G, \tag{1.34}
\end{equation*}
$$

to find $\int d x^{1} d x^{2} \vec{\nabla} G=\oint I^{-1} d \mathbf{x} G$, as desireed. In terms of a parameterization $x=x(u, v)$, the pseudoscalar for the space is

$$
\begin{equation*}
I=\frac{\mathbf{x}_{u} \wedge \mathbf{x}_{v}}{J} \tag{1.35}
\end{equation*}
$$

so

$$
\begin{equation*}
I^{-1}=\frac{J}{\mathbf{x}_{u} \wedge \mathbf{x}_{v}} . \tag{1.36}
\end{equation*}
$$

Also note that $\left(\mathbf{x}_{u} \wedge \mathbf{x}_{v}\right)^{-1}=\mathbf{x}^{v} \wedge \mathbf{x}^{u}$, so

$$
\begin{equation*}
I^{-1}=J\left(\mathbf{x}^{v} \wedge \mathbf{x}^{u}\right), \tag{1.37}
\end{equation*}
$$

and

$$
\begin{align*}
I^{-1} d \mathbf{x} & =I^{-1} \cdot d \mathbf{x} \\
& =J\left(\mathbf{x}^{v} \wedge \mathbf{x}^{u}\right) \cdot\left(\mathbf{x}_{u} d u-\mathbf{x}_{v} d v\right)  \tag{1.38}\\
& =J\left(\mathbf{x}^{v} d u+\mathbf{x}^{u} d v\right),
\end{align*}
$$

so the right acting gradient integral is

$$
\begin{equation*}
\int J d u d v \nabla G=\left.\int J \mathbf{x}^{v} G\right|_{\Delta v} d u+\left.J \mathbf{x}^{u} G d v\right|_{\Delta u}, \tag{1.39}
\end{equation*}
$$

which we write in abbreviated form as $\int J\left(\mathbf{x}^{v} d u+\mathbf{x}^{u} d v\right) G$.
For the $G=1$ case, from eq. (1.33) we find

$$
\begin{equation*}
\int J d u d v F I \overleftarrow{\nabla} I^{-1}=\oint F d \mathbf{x} I^{-1} \tag{1.40}
\end{equation*}
$$

However, in a 2D space, regardless of metric, we have $I a=-a I$ for any vector $a$ (i.e. $\nabla$ or $d \mathbf{x}$ ), so we may commute the outer pseudoscalars in

$$
\begin{gather*}
\int J d u d v F I \overleftarrow{\nabla} I^{-1}=\oint F d \mathbf{x} I^{-1},  \tag{1.41}\\
-\int J d u d v F I I^{-1} \stackrel{\leftarrow}{\nabla}=-\oint F I^{-1} d \mathbf{x} \tag{1.42}
\end{gather*}
$$

After cancelling the negative sign on both sides, we have the claimed result.
To see that $I a$, for any vector $a$ is normal to $a$, we can compute the dot product

$$
\begin{equation*}
(I a) \cdot a=\langle I a a\rangle=a^{2}\langle I\rangle=0 \tag{1.43}
\end{equation*}
$$

since the scalar selection of a bivector is zero. Since $I^{-1}= \pm I$, the same argument shows that $I^{-1} d \mathbf{x}$ must be orthogonal to $d \mathbf{x}$.

Let's look at the geometry of the normal $I^{-1} \mathbf{x}$ in a couple 2 D vector spaces. We use an integration volume of a unit square to simplify the boundary term expressions.

- Euclidean: With a parameterization $x(u, v)=u \mathbf{e}_{1}+v \mathbf{e}_{2}$, and Euclidean basis vectors $\left(\mathbf{e}_{1}\right)^{2}=\left(\mathbf{e}_{2}\right)^{2}=1$, the fundamental theorem integrated over the rectangle $\left[x_{0}, x_{1}\right] \times\left[y_{0}, y_{1}\right]$ is

$$
\begin{equation*}
\int d x d y \nabla G=\int \mathbf{e}_{2}\left(G\left(x, y_{1}\right)-G\left(x, y_{0}\right)\right) d x+\mathbf{e}_{1}\left(G\left(x_{1}, y\right)-G\left(x_{0}, y\right)\right) d y \tag{1.44}
\end{equation*}
$$

Each of the terms in the integrand above are illustrated in fig. 1.4, and we see that this is a path integral weighted by the outwards normal.


Figure 1.4: Outwards oriented normal for Euclidean space.

- Spacetime: Let $x(u, v)=u \gamma_{0}+v \gamma_{1}$, where $\left(\gamma_{0}\right)^{2}=-\left(\gamma_{1}\right)^{2}=1$. With $u=t, v=x$, the gradient integral over a $\left[t_{0}, t_{1}\right] \times\left[x_{0}, x_{1}\right]$ of spacetime is

$$
\begin{align*}
\int d t d x \nabla G & =\int \gamma^{1} d t\left(G\left(t, x_{1}\right)-G\left(t, x_{0}\right)\right)+\gamma^{0} d x\left(G\left(t_{1}, x\right)-G\left(t_{1}, x\right)\right)  \tag{1.45}\\
& =\int \gamma_{1} d t\left(-G\left(t, x_{1}\right)+G\left(t, x_{0}\right)\right)+\gamma_{0} d x\left(G\left(t_{1}, x\right)-G\left(t_{1}, x\right)\right)
\end{align*}
$$

With $t$ plotted along the horizontal axis, and $x$ along the vertical, each of the terms of this integrand is illustrated graphically in fig. 1.5. For this mixed signature space, there is no longer any good geometrical characterization of the normal.


Figure 1.5: Orientation of the boundary normal for a spacetime basis.

- Spacelike: Let $x(u, v)=u \gamma_{1}+v \gamma_{2}$, where $\left(\gamma_{1}\right)^{2}=\left(\gamma_{2}\right)^{2}=-1$. With $u=x, v=y$, the gradient integral over a $\left[x_{0}, x_{1}\right] \times\left[y_{0}, y_{1}\right]$ of this space is

$$
\begin{align*}
\int d x d y \nabla G & =\int \gamma^{2} d x\left(G\left(x, y_{1}\right)-G\left(x, y_{0}\right)\right)+\gamma^{1} d y\left(G\left(x_{1}, y\right)-G\left(x_{1}, y\right)\right) \\
& =\int \gamma_{2} d x\left(-G\left(x, y_{1}\right)+G\left(x, y_{0}\right)\right)+\gamma_{1} d y\left(-G\left(x_{1}, y\right)+G\left(x_{1}, y\right)\right) \tag{1.46}
\end{align*}
$$

Referring to fig. 1.6. where the elements of the integrand are illustrated, we see that the normal $I^{-1} d \mathbf{x}$ for the boundary of this region can be characterized as inwards.


Figure 1.6: Inwards oriented normal for a Dirac spacelike basis.

## Bibliography

[1] S.L. Salas and E. Hille. Calculus: one and several variables. Wiley New York, 1990. 1.1

