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Multivector form of Leibniz integral theorem

1.1 Goal.

Here we will explore the multivector form of the Leibniz integral theorem (aka. Feynman's trick in one dimension), as discussed in [1].

Given a boundary $\Omega(t)$ that varies in time, we seek to evaluate

$$\frac{d}{dt} \int_{\Omega(t)} F d^p \mathbf{x} \stackrel{\leftrightarrow}{\mathbf{\partial}} G. \tag{1.1}$$

Recall that when the bounding volume is fixed, we have

$$\int_{\Omega} F d^{p} \mathbf{x} \stackrel{\leftrightarrow}{\mathbf{\partial}} G = \int_{\partial \Omega} F d^{p-1} \mathbf{x} G, \qquad (1.2)$$

and expect a few terms that are variations of the RHS if we take derivatives.

1.2 Simplest case: scalar function, one variable.

With

$$A(t) = \int_{a(t)}^{b(t)} f(u, t) du,$$
(1.3)

If we can find an antiderivative, such that

$$\frac{\partial F(u,t)}{\partial u} = f(u,t), \tag{1.4}$$

or

$$F(u,t) = \int f(u,t)du.$$
(1.5)

The integral is made trivial

$$A(t) = \int_{a(t)}^{b(t)} f(u, t) du$$

=
$$\int_{a(t)}^{b(t)} \frac{\partial F(u, t)}{\partial u} du$$

=
$$F(b(t), t) - F(a(t), t).$$
 (1.6)

Should we attempt to take derivatives, we have a contribution from the first parameter that is entirely dependent on the boundary, and a contribution from the second parameter that is entirely independent of the boundary. That is

$$\frac{d}{dt} \int_{a(t)}^{b(t)} f(u,t) du = \frac{\partial F}{\partial b} \frac{\partial b}{\partial t} - \frac{\partial F}{\partial a} \frac{\partial a}{\partial t} + \frac{\partial F(u,t)}{\partial t} \Big|_{u=a(t)}^{b(t)} = f(b(t),t)b'(t) - f(a(t),t)a'(t) + \int_{a(t)}^{b(t)} \frac{\partial}{\partial t} f(u,t) du.$$
(1.7)

In the second step, the antiderivative function F has been restated in it's original integral form eq. (1.5). We are able to take the derivative into the integral, since we first evaluate that derivative, independent of the boundary, and then evaluate the result at the respective end points of the boundary.

1.3 Next simplest case: Multivector line integral (perfect derivative.)

Given an *N* dimensional vector space, and a path parameterized by vector $\mathbf{x} = \mathbf{x}(u)$. The line integral special case of the fundamental theorem of calculus is found by evaluating

$$\int F(u)d\mathbf{x} \stackrel{\leftrightarrow}{\mathbf{\partial}} G(u), \tag{1.8}$$

where *F*, *G* are multivectors, and

$$d\mathbf{x} = \frac{\partial \mathbf{x}}{\partial u} du = \mathbf{x}_u du$$

$$\stackrel{\leftrightarrow}{\partial} = \mathbf{x}^u \frac{\stackrel{\leftrightarrow}{\partial}}{\partial u'},$$
(1.9)

where $\mathbf{x}_{u}\mathbf{x}^{u} = \mathbf{x}_{u} \cdot \mathbf{x}^{u} = 1$.

Evaluating the integral, we have

$$\int F(u)d\mathbf{x} \stackrel{\leftrightarrow}{\partial} G(u) = \int F(u)\mathbf{x}_u du\mathbf{x}^u \stackrel{\leftrightarrow}{\partial} \frac{\partial}{\partial u} G(u)$$

$$= \int du \frac{\partial}{\partial u} (F(u)G(u))$$

$$= F(u)G(u).$$
(1.10)

If we allow F, G, \mathbf{x} to each have time dependence

$$F = F(u, t)$$

$$G = G(u, t)$$

$$\mathbf{x} = \mathbf{x}(u, t),$$

(1.11)

so we have

$$\frac{d}{dt} \int_{u=a(t)}^{b(t)} F(u,t) d\mathbf{x} \stackrel{\leftrightarrow}{\partial} G(u,t) = \frac{du}{dt} \frac{\partial}{\partial u} \left(F(u,t)G(u,t) \right) \Big|_{u=a(t)}^{b(t)} + \frac{d}{dt} \left(F(u,t)G(u,t) \right) \Big|_{u=a(t)}^{b(t)}.$$
(1.12)

1.4 General multivector line integral.

Now suppose that we have a general multivector line integral

$$A(t) = \int_{a(t)}^{b(t)} F(u, t) d\mathbf{x} G(u, t),$$
(1.13)

where $d\mathbf{x} = \mathbf{x}_u du$, $\mathbf{x}_u = \partial \mathbf{x}(u, t) / \partial u$. Writing out the integrand explicitly, we have

$$A(t) = \int_{a(t)}^{b(t)} du F(u, t) \mathbf{x}_u(u, t) G(u, t).$$
(1.14)

Following our logic with the first scalar case, let

$$\frac{\partial B(u,t)}{\partial u} = F(u,t)\mathbf{x}_u(u,t)G(u,t).$$
(1.15)

We can now evaluate the derivative

$$\frac{dA(t)}{dt} = \left. \frac{du}{dt} \frac{\partial B}{\partial u} \right|_{u=a(t)}^{b(t)} + \left. \frac{\partial}{\partial t} B(u,t) \right|_{u=a(t)}^{b(t)}.$$
(1.16)

Writing eq. (1.15) in integral form, we have

$$B(u,t) = \int du F(u,t) \mathbf{x}_u(u,t) G(u,t), \qquad (1.17)$$

 \mathbf{SO}

$$\frac{dA(t)}{dt} = \left. \frac{du}{dt} \frac{\partial B}{\partial u} \right|_{u=a(t)}^{b(t)} + \left. \frac{\partial}{\partial t'} \int_{a(t)}^{b(t)} du F(u, t') d\mathbf{x}_u(u, t') G(u, t') \right|_{t'=t} = \left. \frac{du}{dt} F(u, t) \mathbf{x}_u(u, t) G(u, t) \right|_{u=a(t)}^{b(t)} + \left. \int_{a(t)}^{b(t)} \frac{\partial}{\partial t} F(u, t) d\mathbf{x}(u, t) G(u, t) \right|_{t'=t} \tag{1.18}$$

$$\frac{d}{dt} \int_{a(t)}^{b(t)} F(u,t) d\mathbf{x}(u,t) G(u,t) = F(u,t) \frac{d\mathbf{x}}{dt}(u,t) G(u,t) \Big|_{u=a(t)}^{b(t)} + \int_{a(t)}^{b(t)} \frac{\partial}{\partial t} F(u,t) d\mathbf{x}(u,t) G(u,t).$$
(1.19)

This is perhaps clearer, if just written as:

$$\frac{d}{dt} \int_{a(t)}^{b(t)} F d\mathbf{x} G = F \frac{d\mathbf{x}}{dt} G \Big|_{u=a(t)}^{b(t)} + \int_{a(t)}^{b(t)} \frac{\partial}{\partial t} F d\mathbf{x} G.$$
(1.20)

As a check, it's worth pointing out that we can recover the one dimensional result, writing $\mathbf{x} = u\mathbf{e}_1$, $f = F\mathbf{e}_1^{-1}$, and G = 1, for

$$\frac{d}{dt} \int_{a(t)}^{b(t)} f du = f(u) \frac{du}{dt} \Big|_{u=a(t)}^{b(t)} + \int_{a(t)}^{b(t)} du \frac{\partial f}{\partial t}.$$
(1.21)

1.5 Next steps.

I've tried a couple times on paper to do surface integral variations of this (allowing the surface to vary with time), and don't think that I've gotten it right. Will try again (or perhaps just look it up and see what the result is supposed to look like, then see how that translates into the GC formalism.)

Bibliography

 Wikipedia contributors. Leibniz integral rule — Wikipedia, the free encyclopedia. https://en. wikipedia.org/w/index.php?title=Leibniz_integral_rule&oldid=1223666713, 2024. [Online; accessed 22-May-2024]. 1.1